

12. An industrial robot having a swivel, comprising:
two coaxial, mutually rotatable members and having means for transferring operating and/or controlling media between the members, wherein said means are flexible hoses or cables between the members.
13. The robot according to claim 12, wherein the means are elastically extensible.
14. The robot according to claim 13, wherein said means are spiral hoses or cables.
15. The robot according to claim 13, wherein the means are connected to the members by means of quick-couplings.
16. The robot according to claim 12, wherein a cylindrical housing for enclosing said means between the two members is provided.
17. The robot according to claim 12, wherein one of the members is a lower connection ring and the other member is a cover, the cover being connected to a central shaft, in relation to which the lower connection ring is journalled.
18. The robot according to claim 17, wherein the cover is connected to the central shaft by means of a quick-coupling.

19. The robot according to claim 17, wherein the lower connection ring and the cover are provided with through connection holes.

20. The robot according to claim 17, wherein the central shaft is arranged on a base plate.

21. The robot according to claim 12, wherein the mutual rotation between the two members is limited to no more than one full revolution.